

STUDYING THE MOVEMENT OF A HORIZONTAL MOVING BODY TAKING INTO ACCOUNT THE RESISTANCE OF THE ENVIRONMENT AND SOLVING RELATED PROBLEMS

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ANNOTATION

This article examines the laws of motion in the horizontal plane of a ship under the influence of the resistance force of water, as well as the impact of the resistance of air and the friction force of the surface, and issues related to them are worked out.

Keywords: acceleration; the equation of motion; the equation velocity; the equation of motion; force of resistance; to take an integral; limits of integral; resistance of an air.

GORIZONTAL HARAKATLANAYOTGAN JISMNING HARAKATINI MUHITNING QARSHILIGINI E'TIBORGA OLGAN HOLDA O'RGANISH VA UNGA DOIR MASALALAR YECHISH

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Annotatsiya

Ushbu maqolada suvning qarshilik kuchi ta'siridagi kemaning hamda havoning qarshilik va sirtning ishqalanish kuchi ta'siridagi avtomobilning gorizontal tekislikdagi harakat qonunlari o'rganilgan va ularga oid masalalar ishlab ko'rsatilgan.

Калит сўзлар: тезланиши; ҳаракат тенгламаси; тезлик тенгламаси; дифференциал тенглама; қаршилик кучи; интеграллаш; интеграл чегаралари; ҳавонинг қаршилиги.

ИЗУЧЕНИЕ ДВИЖЕНИЯ ГОРИЗОНТАЛЬНО ДВИЖУЩЕГОСЯ ТЕЛА С УЧЕТОМ СОПРОТИВЛЕНИЯ СРЕДЫ И РЕШЕНИЕ СВЯЗАННЫХ ЗАДАЧ.

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АННОТАЦИЯ

В данной статье изучены законы движения судна в горизонтальной плоскости под действием силы сопротивления воды, а также транспортного средства под действием сопротивления воздуха и силы поверхностного трения и разработаны вопросы, связанные с ними.

Ключевые слова: ускорение; уравнение движения; уравнение скорости; дифференциальное уравнение; сила сопротивления; интегрирование; пределы интеграла; сопротивление воздуху.

KIRISH

Ma'lumki, umumta'lim o'rta maktablarining yuqori sinflari hamda akademik litsey o'quvchilariga biror sirtda sirpanib harakatlanayotgan jismning harakatini o'rganish mavzulari juda ham mukammal darajada yoritilgan. Oliy ta'lif muassasalarida ham bu masala chuqurlashtirib differential va vektor ko'rinishlarida o'qitiladi. Aslida, jism harakatlanganda faqat sirtning sirpanish ishqalanishi ta'sir qilmasdan, balki havoning qarshiligi ham ta'sir etadi. Undan tashqari suyuqlikda harakatlanayotgan jismga ham suyuqlik tomonidan qarshilik kuchi ta'sir etadi. Real holatda jismning havo yoki suyuqlik qarshiligi e'tiborga olinadigan holdagi harakati haqiqatga ancha yaqin bo'lib, bunga esa oliy ta'lif muassasalarida kam e'tibor beriladi. SHuning uchun ham sirtning ishqalanish kuchi va muhitning qarshiligini birgalikda e'tiborga olingan holdagi jismning harakatini o'rganish talabalarni real vaziyatga ancha yaqinlashtiradi.

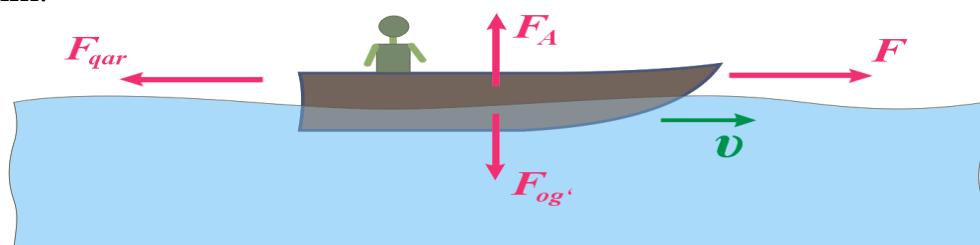
Bilamizki, muhitning qarshiligi tezlikning birinchi darajasiga yoki ikkinchi darajasiga to'g'ri proporsional bo'lishi mukin. Masalan, suyuqlik bilan sodir bo'ladigan hodisalarda (qayiq uoki kemaning harakatini o'rganishda) qarshilik kuchi tezlikning birinchi darajasiga proporsional bo'lsa, havo bilan sodir bo'ladigan hodisalarda (avtomobil harakatini o'rganishda, aviatsiyada, harbiy texnikada parashyut, o'q, snaryad va boshqalarni o'rganishda) qarshilik kuchini tezlikning ikkinchi darajasiga proporsional bo'ladi. Biz ushbu maqolada suyuqlik sirtida suzayotgan kema yoki qayiqning suvning qarshiligi ta'siridagi harakatini hamda gorizontall sirtda harakatlanayotgan avtomobilning sirtning ishqalanish kuchi va havoning qarshiliginig birgalikdagi ta'siri ostidagi harakatini alohida-alohida o'rganamiz va ularga oid masalalar ishlaymiz.

ADABIYOTLAR TAHLILI VA METODOLOGIYASI

I.

Qayiq yoki kema suyuqlik sirtida suzayotganda unga quyidagi kuchlar ta'sir qiladi (1-rasm):

- F_{og} — pastga yo'nalgan og'irlik kuchi hamda bu kuch bilan kompensatsiyalanuvchi $\vec{F}_A = -\vec{F}_{og}$. Arximed kuchi;
- $F_{qar} = \alpha \vartheta$ — suyuqlikning qayiq harakatiga ko'rsatadigan qarshilik kuchi (kichik tezliklarda $F_{qar} \sim \vartheta$ bo'ladi);
- F — qayiqga ta'sir qiluvchi tezlatuvchi yoki sekinlatuvchi kuchi bo'lib, u motorining tortish kuchi uchun $F > 0$ ishorali yoki tormozlangandagi tormoz kuchi uchun $F < 0$ ishorali bo'lishi mumkin.



1-rasm

Yuqorida sanab o'tilgan kuchlar ta'sirida harakatlanayotgan qayiq uchun dinamikaning 2-qonuni qo'llaymiz va shu asosda differensial tenglama hosil qilib uni ishlab chiqamiz.

$$ma = F - F_{qar}, \rightarrow m \frac{d\vartheta}{dt} = F - \alpha\vartheta, \rightarrow dt = \frac{m d\vartheta}{F - \alpha\vartheta} = -\frac{m}{\alpha} \cdot \frac{d\vartheta}{\vartheta - \frac{F}{\alpha}}$$

$$\int_0^t dt = -\frac{m}{\alpha} \cdot \int_{\vartheta_0}^{\vartheta} \frac{d\vartheta}{\vartheta - \frac{F}{\alpha}}, \rightarrow t = -\frac{m}{\alpha} \cdot \ln \left| \vartheta - \frac{F}{\alpha} \right| \Big|_{\vartheta_0}^{\vartheta} = -\frac{m}{\alpha} \cdot \ln \left| \frac{\vartheta - \frac{F}{\alpha}}{\vartheta_0 - \frac{F}{\alpha}} \right| =$$

$$= \frac{m}{\alpha} \cdot \ln \left| \frac{\vartheta_0 - \frac{F}{\alpha}}{\vartheta - \frac{F}{\alpha}} \right| = \frac{m}{\alpha} \cdot \ln \left| \frac{\alpha\vartheta_0 - F}{\alpha\vartheta - F} \right|$$

Demak, differensial tenglamani yechish natijasida gorizontal yo'lda kichik tezlikda harakatalanayotgan avtomobil yoki velosipedning ixtiyoriy ϑ tezlikka erishish vaqtini quyidagicha bo'lar ekan:

$$t = \frac{m}{\alpha} \cdot \ln \left| \frac{F - \alpha\vartheta_0}{F - \alpha\vartheta} \right| \quad (\text{I. 1})$$

Yuqoridagi (I.1) formulada tortish kuchi suyuqlikning qarshilik kuchidan kichik bo'lsa ($F < \alpha\vartheta_0$), u holda qayiq sekinlanuvchan harakat qiladi va tezlikning miqdori biror ϑ qiymatga erishgach $F = \alpha\vartheta$ bo'ladi va shu erishgan tezlikda harakatni davom ettiradi.

Yuqoridagi (I.1) formulada tortish kuchi suyuqlikning qarshilik kuchidan katta bo'lsa ($F > \alpha\vartheta_0$), u holda qayiq tezlanuvchan harakat qiladi va tezlikning miqdori biror ϑ qiymatga erishgach $F = \alpha\vartheta$ bo'ladi va shu erishgan tezlikda harakatni davom ettiradi.

Yuqoridagi (I.1) formuladan ϑ tezlikni topib olsak, u holda $\vartheta = \vartheta(t)$ ko'rinishdagi oniy tezlik formulasiga ega bo'lamiz. Shu formulani keltririb chiqarayik.

$$t = -\frac{m}{\alpha} \cdot \ln \left| \frac{\vartheta - \frac{F}{\alpha}}{\vartheta_0 - \frac{F}{\alpha}} \right|, \rightarrow \frac{\vartheta - \frac{F}{\alpha}}{\vartheta_0 - \frac{F}{\alpha}} = e^{-\frac{\alpha}{m}t}, \rightarrow$$

$$\vartheta - \frac{F}{\alpha} = \left(\vartheta_0 - \frac{F}{\alpha} \right) e^{-\frac{\alpha}{m}t}, \rightarrow \vartheta = \left(\vartheta_0 - \frac{F}{\alpha} \right) e^{-\frac{\alpha}{m}t} + \frac{F}{\alpha}$$

$$\vartheta = \left(\vartheta_0 - \frac{F}{\alpha} \right) e^{-\frac{\alpha}{m}t} + \frac{F}{\alpha} \quad (\text{I.2})$$

Yuqoridagi (I.2) formulada $t \rightarrow \infty$ bo'lganda bitta had qoladi va avtomobil yoki velosiped erishadigan eng katta tezlikni aniqlash mumkin.

$$\vartheta_{\max} = \frac{F}{\alpha} \quad (\text{I.3})$$

Yuqoridagi (I.3) formulani dinamikaning asosiy tenglamasidan ham hosil qilish mumkin.

$$ma = F - F_{qar} = 0, \rightarrow F_{qar} = F, \rightarrow \alpha\vartheta = F, \rightarrow \vartheta_{\max} = \frac{F}{\alpha}$$

Shuni alohida eslatib o'tish kerakki, (6.23) formula sharti, ya'ni maksimal tezlikka erishish sharti faqat $F > f_{mg}$ bo'lgandagina bajariladi. Chunki, bunda avtomobil yoki velosiped tezlanuvchan harakat qiladi.

Agar (7.3) formulani e'tiborga oladigan bo'lsak, u holda (I.1) va (I.2) formulalarni maksimal tezlik orqali quyidagicha yozishimiz mumkin:

$$t = \frac{m}{\alpha} \cdot \ln \left| \frac{\vartheta_{\max} - \vartheta_0}{\vartheta_{\max} - \vartheta} \right| \quad (\text{I.1}')$$

$$\vartheta = \vartheta_{\max} - (\vartheta_{\max} - \vartheta_0) e^{-\frac{\alpha}{m} t} \quad (\text{I.2}')$$

Endi esa 1-rasmdagi holat uchun yo'l va tezlik orasidagi bog'lanishni, ya'ni $s=s(\vartheta)$ tenglamani hosil qilaylik. Buning uchun yuqorida keltirib chiqarilgan tenglamalar kabi dinamikaning asosiy tenglamasidan foydalanib differensial tenglama hosil qilamiz va uni yechib chiqamiz.

$$\begin{aligned} m \frac{d\vartheta}{dt} \cdot \frac{dx}{dx} &= F - \alpha \vartheta, \rightarrow m \frac{\vartheta d\vartheta}{dx} = F - \alpha \vartheta, \rightarrow dx = \frac{m \vartheta d\vartheta}{F - \alpha \vartheta} = \\ &= -\frac{m}{\alpha} \cdot \frac{\vartheta d\vartheta}{\vartheta - \frac{F}{\alpha}} = -\frac{m}{\alpha} \cdot \left(1 + \frac{\frac{F}{\alpha}}{\vartheta - \frac{F}{\alpha}} \right) d\vartheta. \\ s &= \int_0^s dx = -\frac{m}{\alpha} \cdot \int_{\vartheta_0}^{\vartheta} \left(1 + \frac{\frac{F}{\alpha}}{\vartheta - \frac{F}{\alpha}} \right) d\vartheta = -\frac{m}{\alpha} \cdot \left[\vartheta + \frac{F}{\alpha} \cdot \ln \left| \vartheta - \frac{F}{\alpha} \right| \right] \Big|_{\vartheta_0}^{\vartheta} = \\ &= -\frac{m}{\alpha} \cdot \left[\vartheta - \vartheta_0 + \frac{F}{\alpha} \cdot \ln \left| \frac{\vartheta - \frac{F}{\alpha}}{\vartheta_0 - \frac{F}{\alpha}} \right| \right] = \frac{m}{\alpha} \cdot \left[\vartheta_0 - \vartheta + \frac{F}{\alpha} \cdot \ln \left| \frac{\alpha \vartheta_0 - F}{\alpha \vartheta - F} \right| \right]. \\ \text{yoki } s &= \frac{m}{\alpha} \cdot \left[\vartheta_0 - \vartheta + \vartheta_{\max} \cdot \ln \left| \frac{\vartheta_{\max} - \vartheta_0}{\vartheta_{\max} - \vartheta} \right| \right] \end{aligned}$$

Shunday qilib, $s=s(\vartheta)$ tenglamani hosil qildik.

$$s = \frac{m}{\alpha} \cdot \left[\vartheta_0 - \vartheta + \frac{F}{\alpha} \cdot \ln \left| \frac{\alpha \vartheta_0 - F}{\alpha \vartheta - F} \right| \right] \quad (\text{I.4})$$

$$s = \frac{m}{\alpha} \cdot \left[\vartheta_0 - \vartheta + \vartheta_{\max} \cdot \ln \left| \frac{\vartheta_{\max} - \vartheta_0}{\vartheta_{\max} - \vartheta} \right| \right] \quad (\text{I.4}')$$

Yuqoridagi (I.4) va (I.4') formulalar jism ixtiyoriy ϑ tezlikka erishish uchun qanday s masofani bosib o'tish kerakligini aniqlaydigan formulalardir.

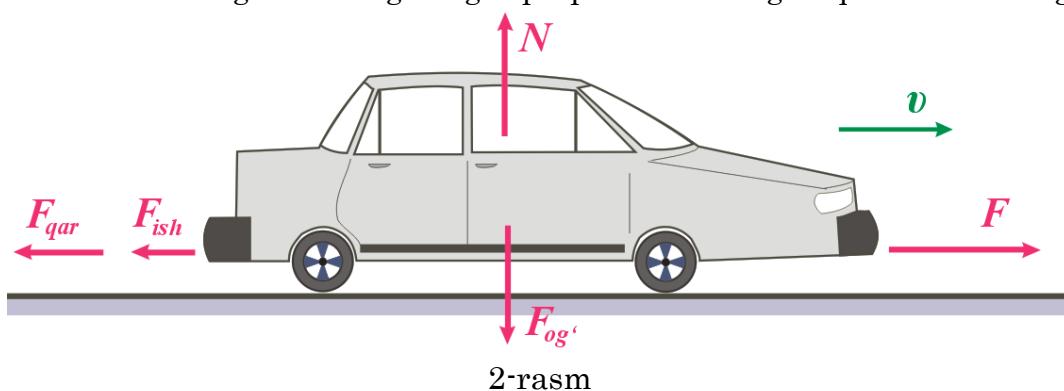
Agar biror boshlang'ich ϑ_0 tezlikka ega bo'lgan qayiqga F tortish yoki tormoz kuchi ta'sir etmasa, u holda (I.4) formula quyidagi soddarroq ko'rinishga o'tadi:

$$s = \frac{m}{\alpha} \cdot (\vartheta_0 - \vartheta) \quad (\text{I.4a})$$

Bu keltirib chiqarilgan barcha formulalar velosiped harakati yoki nisbatan kichik tezlikda harakatlanayotgan avtomobil uchun, ya’ni muhitning qarshilik kuchi tezlikning birinchi darajasiga bog’liq bo’lgan hol uchun o’rinlidir.

II. Endi esa gorizontal yo’lda harakatlanayotgan jismning umumiyl holdagi harakatini o’rganaylik. Qayiq, kema yoki kater harakatiga nisbatan avtomobillar nisbatan tezroq harakatlangani uchun avtomobilgarga tezlikning kvadratiga proporsional bo’lgan havoning qarshilik kuchi ta’sir etasdi deb qaraymiz.

Avtomobil nisbatan tez harakatlanayotgan hol degani bu tezlikning biror kritik qiymatidan kattaroq tezlikda harakatlanish deganidir. Boshqacha aytganda, avtomobil kuzoviga yaqin sohadagi qatlam-qatlam havo oqimlari aralashib girdoblarga aylanadi. Bunda avtomobil havo oqimi tomonidan tezlikning kvadratiga to’g’ri proporsional bo’lgan qarshilik kuchiga uchraydi.



2-rasm

Talabalarga bu mavzuni o’qitishda jismga ta’sir qiladigan kuchlarni to’g’ri joytirishlariga e’tibor qilish kerak. Gorizontal yo’lda harakatlanayotgan avtomobilga quyidagi kuchlar ta’sir qiladi (2-rasm):

— $F_{og} = mg$ – pastga yo’nalgan og’irlilik kuchi hamda bu kuch bilan kompensatsiyalanuvchi $\vec{N} = -\vec{F}_{og}$ sirtning yuqoriga yo’nalgan reaksiya kuchi;

— $F_{ishq} = \frac{x}{R}mg = fmg$ – dumalashdagi ishqalanish kuchi; x – dumalashdagi ishqalanish koeffitsiyenti; R – avtomobilning g’ildiragi radiusi; $f = \frac{x}{R}$ – dumalashdagi qarshilik

koeffitsiyenti, ya’ni avtomobilni joyidan qo’zg’atish uchun kerak bo’lgan kuch avtomobil og’irligining qanday qismini tashkil etishini bildiruvchi koeffitsiyent;

— $F_{qar} = \alpha \vartheta$ – dumalashdagi ishqalanish kuchi (kichik tezliklarda $F_{qar} \sim \vartheta$ bo’ladi);

— F – avtomobilga ta’sir qiluvchi tezlatuvchi yoki sekinlatuvchi kuchi bo’lib, u motorining tortish kuchi uchun $F > 0$ ishorali yoki tormozlangandagi tormoz kuchi uchun $F < 0$ ishorali bo’lishi mumkin.

Rasmda ko’rsatilgani kabi avtomobilga ta’sir qilayotgan kuchlar uchun dinamikaning 2-qonuni qollaymiz va shu asosda differensial tenglama hosil qilib uni ishlab chiqamiz.

$$ma = F - F_{ishq} - F_{qar}, \rightarrow m \frac{d\vartheta}{dt} = F - fmg - \beta\vartheta^2, \rightarrow$$

$$dt = \frac{m d\vartheta}{F - fmg - \beta\vartheta^2} = -\frac{m}{\beta} \cdot \frac{d\vartheta}{\vartheta^2 - \frac{F - fmg}{\beta}}$$

Demak, bizda

$$dt = -\frac{m}{\beta} \cdot \frac{d\vartheta}{\vartheta^2 - \frac{F - fmg}{\beta}} \quad (*)$$

ko'rinishidagi differensial tenglama hosil bo'ldi. Bu differensial tenglamadagi tenglamani $\frac{F - fmg}{\beta}$ ifodaning musbat yoki manfiy bo'lishi, ya'ni $F > fmg$ yoki $F < fmg$ bo'lishiga qarab differensial tenglama yechishning keyingi qadami ikki xil yo'ldan boradi.

A) $F > fmg$ bo'lganda $\frac{F - fmg}{\beta} > 0$ bo'ladi va (*) differensial tenglamani yechishda matematikadan $\int \frac{dx}{x^2 - a^2} = \frac{1}{2a} \ln \left| \frac{x-a}{x+a} \right| + C$ integrallash formulasidan foydalanamiz;

B) $F < fmg$ bo'lganda $\frac{F - fmg}{\beta} < 0$ bo'ladi va (*) differensial tenglamani yechishda matematikadan $\int \frac{dx}{x^2 + a^2} = \frac{1}{a} \operatorname{arctg} \frac{x}{a} + C$ integrallash formulasidan foydalanamiz;

Dastlab biz A) shartga bo'ysungan hol uchun differensial tenglamani yechib $t=t(\vartheta)$ bog'lanishni, ya'ni avtomobilning ixtiyoriy ϑ tezlikka erishadigan vaqt onini topish formulasini keltirib chiqaramiz.

$$\int_0^t dt = -\frac{m}{\beta} \cdot \int_{\vartheta_0}^{\vartheta} \frac{d\vartheta}{\vartheta^2 - \frac{F - fmg}{\beta}}, \rightarrow t = -\frac{m}{\beta} \cdot \frac{\sqrt{\beta}}{2\sqrt{F - fmg}} \cdot \ln \left| \frac{\vartheta - \sqrt{\frac{F - fmg}{\beta}}}{\vartheta + \sqrt{\frac{F - fmg}{\beta}}} \right| \Big|_{\vartheta_0}^{\vartheta} =$$

$$= \frac{m}{2\sqrt{\beta(F - fmg)}} \cdot \ln \left| \frac{\vartheta + \sqrt{\frac{F - fmg}{\beta}}}{\vartheta - \sqrt{\frac{F - fmg}{\beta}}} \cdot \frac{\vartheta_0 - \sqrt{\frac{F - fmg}{\beta}}}{\vartheta_0 + \sqrt{\frac{F - fmg}{\beta}}} \right|$$

Demak, (*) differensial tenglamaning A) shart bo'yicha yechish natijasida gorizontal yo'lda katta tezlikda harakatalanayotgan avtomobilning ixtiyoriy ϑ tezlikka erishish vaqtini quyidagicha bo'lar ekan:

$$t = \frac{m}{2\sqrt{\beta(F - fmg)}} \cdot \ln \left| \frac{\sqrt{\frac{F - fmg}{\beta}} + \vartheta}{\sqrt{\frac{F - fmg}{\beta}} - \vartheta} \cdot \frac{\sqrt{\frac{F - fmg}{\beta}} - \vartheta_0}{\sqrt{\frac{F - fmg}{\beta}} + \vartheta_0} \right| \quad (\text{II.9})$$

Bu shartda $F > fmg$ ekanligidan avtomobil faqat tezlanuvchan harakat qilishi kelib chiqadi. Tezlik oshgan sari esa qarshilik kuchi ortib boradi biror maksimal tezlikka erishganda qarshilik va ishqalanish kuchlari tortishish kuchiga teng bo'lib qoladi. Bu maksimal tezlikni dinamikaning 2-qonunidan osongina topish mumkin.

$$ma = F - F_{ishq} - F_{qar} = 0, \rightarrow F_{qar} = F - F_{ishq}, \rightarrow \beta g^2 = F - fmg, \rightarrow g_{\max} = \sqrt{\frac{F - fmg}{\beta}}$$

$$g_{\max} = \sqrt{\frac{F - fmg}{\beta}} \quad (\text{II.10})$$

(II.10) formulani e'tiborga olsak, (II.9) formulani quyidagicha ifodalshimiz mumkin bo'ladi:

$$t = \frac{m}{2\beta g_{\max}} \cdot \ln \left| \frac{g_{\max} + g}{g_{\max} - g} \cdot \frac{g_{\max} - g_0}{g_{\max} + g_0} \right| \quad (\text{II.9}')$$

Agar avtomobil tinch holatdan harakat boshlagan bo'lsa, u holda (II.9) va (II.9') formulalar quyidagi ko'rinishlarga o'tadi:

$$t = \frac{m}{2\sqrt{\beta(F - fmg)}} \cdot \ln \left| \frac{\sqrt{\frac{F - fmg}{\beta}} + g}{\sqrt{\frac{F - fmg}{\beta}} - g} \right| \quad (\text{II.9a})$$

$$t = \frac{m}{2\beta g_{\max}} \cdot \ln \left| \frac{g_{\max} + g}{g_{\max} - g} \right| \quad (\text{II.9'a})$$

Endi esa biz **B)** shartga bo'ysungan hol uchun differensial tenglamani yechib $t=t(\vartheta)$ bog'lanishni, ya'ni avtomobilning ixtiyoriy ϑ tezlikka erishadigan vaqt onini topish formulasini keltirib chiqaramiz.

$$\int_0^t dt = -\frac{m}{\beta} \cdot \int_{g_0}^g \frac{d\vartheta}{g^2 - \frac{F - fmg}{\beta}} = -\frac{m}{\beta} \cdot \int_{g_0}^g \frac{d\vartheta}{g^2 + \frac{fmg - F}{\beta}}, \rightarrow t = -\frac{m}{\beta} \cdot \frac{\sqrt{\beta}}{\sqrt{fmg - F}} \cdot$$

$$\cdot \operatorname{arctg} \left(g \sqrt{\frac{\beta}{fmg - F}} \right) \Big|_{g_0}^g = -\frac{m}{\sqrt{\beta(fmg - F)}} \cdot \left[\operatorname{arctg} \left(g \sqrt{\frac{\beta}{fmg - F}} \right) - \operatorname{arctg} \left(g_0 \sqrt{\frac{\beta}{fmg - F}} \right) \right] =$$

$$= \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \left[\operatorname{arctg} \left(g_0 \sqrt{\frac{\beta}{fmg - F}} \right) - \operatorname{arctg} \left(g \sqrt{\frac{\beta}{fmg - F}} \right) \right].$$

Bu yerda biz matematikadan ma'lum bo'lgan

$$\operatorname{arctgx} - \operatorname{arctgy} = \operatorname{arctg} \frac{x - y}{1 + xy}$$

formulasidan foydalanamiz.

$$t = \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \left[\operatorname{arctg} \left(\vartheta_0 \sqrt{\frac{\beta}{fmg - F}} \right) - \operatorname{arctg} \left(\vartheta \sqrt{\frac{\beta}{fmg - F}} \right) \right] = \\ = \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \operatorname{arctg} \left(\frac{\sqrt{\frac{\beta}{fmg - F}} \cdot (\vartheta_0 - \vartheta)}{1 + \frac{\beta}{fmg - F} \cdot \vartheta_0 \vartheta} \right)$$

Demak, (*) differensial tenglamaning **B)** shart bo'yicha yechish natijasida gorizontal yo'lda katta tezlikda harakatalanayotgan avtomobilning ixtiyoriy ϑ tezlikka erishish vaqtini quyidagicha bo'lar ekan:

$$t = \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \operatorname{arctg} \left(\frac{\sqrt{\frac{\beta}{fmg - F}} \cdot (\vartheta_0 - \vartheta)}{1 + \frac{\beta}{fmg - F} \cdot \vartheta_0 \vartheta} \right) \quad (\text{II.11})$$

Bu shartda $F < fmg$ ekanligidan avtomobil faqat sekinlanuvchan harakat qilishi kelib chiqadi. Natijada, qandaydir vaqtadan keyin avtomobil to'xtaydi ($\vartheta=0$). To'xtash vaqtini quyidagicha bo'ladi:

$$t_{to'xt} = \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \operatorname{arctg} \left(\vartheta_0 \sqrt{\frac{\beta}{fmg - F}} \right) \quad (\text{II.11a})$$

Endi esa 2-rasmdagi holat uchun yo'l va tezlik orasidagi bog'lanishni, ya'ni $s=s(\vartheta)$ tenglamani keltirib chiqaraylik. Buning uchun yuqorida keltirib chiqarilgan tenglamalar kabi dinamikaning asosiy tenglamasidan foydalanib differensial tenglama hosil qilamiz va uni yechib chiqamiz.

$$m \frac{d\vartheta}{dt} \cdot \frac{dx}{dx} = F - fmg - \beta \vartheta^2, \rightarrow m \frac{\vartheta d\vartheta}{dx} = F - fmg - \beta \vartheta^2, \rightarrow dx = \frac{m \vartheta d\vartheta}{F - fmg - \beta \vartheta^2} = \\ = -\frac{m}{\beta} \cdot \frac{\vartheta d\vartheta}{\vartheta^2 - \frac{F - fmg}{\beta}} = -\frac{m}{2\beta} \cdot \frac{d\left(\vartheta^2 - \frac{F - fmg}{\beta}\right)}{\vartheta^2 - \frac{F - fmg}{\beta}}, \rightarrow s = \int_0^s dx = -\frac{m}{2\beta} \cdot \int_{\vartheta_0}^{\vartheta} \frac{d\left(\vartheta^2 - \frac{F - fmg}{\beta}\right)}{\vartheta^2 - \frac{F - fmg}{\beta}} = \\ s = \int_0^s dx = -\frac{m}{2\beta} \cdot \int_{\vartheta_0}^{\vartheta} \frac{d\left(\vartheta^2 - \frac{F - fmg}{\beta}\right)}{\vartheta^2 - \frac{F - fmg}{\beta}} = -\frac{m}{2\beta} \cdot \ln \left| \vartheta^2 - \frac{F - fmg}{\beta} \right| \Big|_{\vartheta_0}^{\vartheta} = -\frac{m}{2\beta} \cdot \ln \left| \frac{\vartheta^2 - \frac{F - fmg}{\beta}}{\vartheta_0^2 - \frac{F - fmg}{\beta}} \right| = \\ = \frac{m}{2\beta} \cdot \ln \left| \frac{\frac{F - fmg}{\beta} - \vartheta_0^2}{\frac{F - fmg}{\beta} - \vartheta^2} \right| = \frac{m}{2\beta} \cdot \ln \left| \frac{F - (fmg - \beta \vartheta_0^2)}{F - (fmg + \beta \vartheta^2)} \right|$$

Shunday qilib, $s=s(\vartheta)$ tenglamani hosil qildik.

$$s = \frac{m}{2\beta} \cdot \ln \left| \frac{\frac{F - fmg}{\beta} - g_0^2}{\frac{F - fmg}{\beta} - g^2} \right| = \frac{m}{2\beta} \cdot \ln \left| \frac{F - (fmg + \beta g_0^2)}{F - (fmg + \beta g^2)} \right| \quad (\text{II.12})$$

Agar boshlang'ch tezlik nolga teng ($\theta_0=0$) bo'lsa, u holda (II.12) formulani quyidagicha ifodalash mumkin bo'ladi:

$$s = \frac{m}{2\beta} \cdot \ln \left| \frac{F - fmg}{F - (fmg + \beta g^2)} \right| \quad (\text{II.12a})$$

Agar $F > fmg$ shart bajarilsa, u holda avtomobil tezlanuvchan harakat qilib, biror maksimal tezlikka erishadi. Bunda (II.10) maksimal tezlik formulasini e'tiborga olsak, u holda (II.12) va (II.12a) formulalarni quyidagicha yozish mumkin:

$$s = \frac{m}{2\beta} \cdot \ln \left| \frac{g_{\max}^2 - g_0^2}{g_{\max}^2 - g^2} \right| \quad (\text{II.12'})$$

$$s = \frac{m}{2\beta} \cdot \ln \left| \frac{g_{\max}^2}{g_{\max}^2 - g^2} \right| \quad (\text{II.12'a})$$

Agar $F < fmg$ shart bajarilsa, u holda avtomobil sekinlanuvchan harakat qilib, biror masofani o'tib to'xtaydi. (II.12) formuladan to'xtash masofasi quyidagicha bo'ladi:

$$s_{to'xt} = \frac{m}{2\beta} \cdot \ln \left| 1 + \frac{\beta g_0^2}{fmg - F} \right| \quad (\text{II.12b})$$

Yuqoridagi (II.12) formuladan foydalanib tezlikning masofaga bog'lanish $\theta=\theta(s)$ formulasini aniqlashimiz mumkin.

$$\begin{aligned} s &= -\frac{m}{2\beta} \cdot \ln \left| \frac{g^2 - \frac{F - fmg}{\beta}}{g_0^2 - \frac{F - fmg}{\beta}} \right|, \quad \rightarrow \quad \frac{g^2 - \frac{F - fmg}{\beta}}{g_0^2 - \frac{F - fmg}{\beta}} = e^{-\frac{2\beta s}{m}}, \rightarrow \\ g^2 - \frac{F - fmg}{\beta} &= \left(g_0^2 - \frac{F - fmg}{\beta} \right) \cdot e^{-\frac{2\beta s}{m}}, \rightarrow \quad g^2 = \left(g_0^2 - \frac{F - fmg}{\beta} \right) \cdot e^{-\frac{2\beta s}{m}} + \frac{F - fmg}{\beta}, \rightarrow \\ g &= \sqrt{\left(g_0^2 - \frac{F - fmg}{\beta} \right) \cdot e^{-\frac{2\beta s}{m}} + \frac{F - fmg}{\beta}} \\ g &= \sqrt{\left(g_0^2 - \frac{F - fmg}{\beta} \right) \cdot e^{-\frac{2\beta s}{m}} + \frac{F - fmg}{\beta}} \quad (\text{II.13}) \end{aligned}$$

Agar $F > fmg$ shart bajarilsa, (II.10) maksimal tezlik formulasini e'tiborga olsak, u holda (II.13) formulani quyidagicha yozish mumkin:

$$g = \sqrt{g_{\max}^2 - \left(g_{\max}^2 - g_0^2 \right) \cdot e^{-\frac{2\beta s}{m}}} \quad (\text{II.13'})$$

MUHOKAMA VA NATIJALAR

Yuqorida keltirib chiqarilgan formulalardan yana bir nechta xususiy formulalar keltirib chiqarish mumkin. Masala ishlash davomida ular bilan tanishib chiqamiz.

III. Endi esa yuqorida keltirib chiqarilgan barcha formulalar yuzasidan bir necha masalalar ishslash orqali bilimlarimizni mustahkamlab olamiz.

1-masala: Massasi m ga teng bo'lgan neft tashuvchi tanker kemasiga $F_{\text{kap}} = -\alpha \vartheta$ qonunga bo'ysunuvchi suvning qarshilik kuchi ta'sir etadi. Tanker qig'oqqa yaqinlashganda motor o'chiriladi. Bunda kemaning tazligi n marta kamayishi uchun qancha vaqt sarf bo'ladi va qancha yo'l bosib o'tiladi? To'xtaguncha jami qancha yo'l bosib o'tiladi?

Yechish: Masala shartiga ko'ra $F = 0$, $\vartheta = \frac{\vartheta_0}{n}$ bo'ladi. Masalani ishslash uchun yuqorida keltirib chiqarilgan (I.1) va (I.4) formulalardan foydalanish etarlidir. (I.1) formulaga ko'ra kema tezligi n marta kamayishi uchun ketgan vaqt

$$t = \frac{m}{\alpha} \cdot \ln \left| \frac{F - \alpha \vartheta_0}{F - \alpha \vartheta} \right| = \frac{m}{\alpha} \cdot \ln \left| \frac{0 - \alpha \vartheta_0}{0 - \alpha \vartheta} \right| = \frac{m}{\alpha} \cdot \ln \left| \frac{\vartheta_0}{\vartheta} \right| = \frac{m}{\alpha} \cdot \ln n$$

bo'ladi. Tezligi n marta kamayguncha kemaning bosib o'tadigan yo'li (I.4) formulaga asosan

$$s = \frac{m}{\alpha} \cdot \left[\vartheta_0 - \vartheta + \frac{F}{\alpha} \cdot \ln \left| \frac{\alpha \vartheta_0 - F}{\alpha \vartheta - F} \right| \right] = \frac{m}{\alpha} \cdot \left[\vartheta_0 - \frac{\vartheta_0}{n} + \frac{0}{\alpha} \cdot \ln \left| \frac{\alpha \vartheta_0 - 0}{\alpha \vartheta - 0} \right| \right] = \frac{n-1}{n} \cdot \frac{m \vartheta_0}{\alpha}$$

bo'ladi. Kema butunlay harakatdan to'xtash uchun esa (I.4) formulaga ko'ra

$$s = \frac{m}{\alpha} \cdot \left[\vartheta_0 - \vartheta + \frac{F}{\alpha} \cdot \ln \left| \frac{\alpha \vartheta_0 - F}{\alpha \vartheta - F} \right| \right] = \frac{m}{\alpha} \cdot \left[\vartheta_0 - 0 + \frac{0}{\alpha} \cdot \ln \left| \frac{\alpha \vartheta_0 - 0}{\alpha \vartheta - 0} \right| \right] = \frac{m \vartheta_0}{\alpha}$$

ga teng yo'lni bosib o'tadi.

2-masala: Massasi m ga teng bo'lgan katerga tezlikning 1-darajasiga proporsional bo'lgan qarshilik kuchi hamda kater motorining o'zgarmas F ga teng tortish kuchi ta'sir etadi. Bunda kema qanday eng katta tezlikka erisha oladi? Maksimal tezlikning 90% iga erishish uchun qancha vaqt sarflanadi va bunda kater qancha masofa bosib o'tadi?

Yechish: Tinch holatdan harakat boshlangani uchun $\vartheta_0 = 0$ bo'ladi. Kater maksimal tezlikka erishganda uning boshqa tezligi oshmaydi, ya'ni tezlanishi nolga aylanadi. Shunga ko'ra maksimal tezlik

$$1) \quad ma = F - \alpha \vartheta = 0, \rightarrow F = \alpha \vartheta_{\max}, \rightarrow \vartheta_{\max} = \frac{F}{\alpha}$$

bo'ladi. Masalaning keyingi shartlarida $\vartheta = 0,9 \vartheta_{\max} = 0,9 \frac{F}{\alpha}$ bo'lguncha qancha vaqt sarflanishi va qancha yo'l bosib o'tilishi so'ralsan. Vaqtini aniqlash uchun (I.1) formuladan foydalanamiz. Unga ko'ra

$$t = \frac{m}{\alpha} \cdot \ln \left| \frac{F - \alpha \vartheta_0}{F - \alpha \vartheta} \right| = \frac{m}{\alpha} \cdot \ln \left| \frac{F - \alpha \cdot 0}{F - \alpha \cdot 0,9 \frac{F}{\alpha}} \right| = \frac{m}{\alpha} \cdot \ln \left| \frac{F}{F - 0,9F} \right| = \frac{m}{\alpha} \cdot \ln 10$$

bo'ladi. Masofani aniqlash uchun (I.1) formuladan foydalanamiz. Unga ko'ra

$$\begin{aligned}
 s &= \frac{m}{\alpha} \cdot \left[g_0 - g + \frac{F}{\alpha} \cdot \ln \left| \frac{\alpha g_0 - F}{\alpha g - F} \right| \right] = \frac{m}{\alpha} \cdot \left[0 - 0,9 \frac{F}{\alpha} + \frac{F}{\alpha} \cdot \ln \left| \frac{0 - F}{\alpha \cdot 0,9 \frac{F}{\alpha} - F} \right| \right] = \\
 &= \frac{m}{\alpha} \left[-0,9 \frac{F}{\alpha} + \frac{F}{\alpha} \cdot \ln 10 \right] = \frac{mF}{\alpha^2} [\ln 10 - 0,9]
 \end{aligned}$$

bo'ldi.

3-masala: Massasi $m=1340$ kg ga teng bo'lgan NEKSIYA avtomobili 4-uzatmada $F=420N$ tortish kuchi ta'sirida maksimal $g_{max}=126$ km/soat tezlik bilan harakatlana oladi. Yo'lning qarshilik koeffitsienti $f=0,025$ ga teng bo'lsa, havoning qarshilik koeffitsienti β nimaga teng? Erkin tushish tezlanishini $g=9,8 m/s^2$ deb oling. Bunda tortish kuchining qanday qismi havoning qarshiligidagi engishga sarf qilinadi?

Yechish: Eng avvalo tezlikning qiymatini XBS sistemasida

$$g_{max} = 126 \frac{\kappa M}{coam} = 35 \frac{M}{c}$$

deb olamiz. Bu masalani yechish uchun yuqoridagi (II.10) formuladan foydalanib β koeffitsient formulasini hisosil qilamiz.

$$g_{max} = \sqrt{\frac{F - fmg}{\beta}}, \rightarrow \beta g_{max}^2 = F - fmg, \rightarrow \beta = \frac{F - fmg}{g_{max}^2}$$

Endi hisob-kitob ishlarini bajaramiz.

$$\beta = \frac{F - fmg}{g_{max}^2} = \frac{420H - 0,025 \cdot 1340 \kappa \cdot 9,8 \frac{M}{c^2}}{\left(35 \frac{M}{c} \right)^2} = \frac{92 \kappa \frac{M}{c^2}}{1225 \frac{M^2}{c^2}} \approx 0,075 \frac{\kappa}{M}$$

Avtomobil harakatiga havoning qarshilik kuchini aniqlaymiz.

$$F_{kapu} = \beta g_{max}^2 = 0,075 \frac{\kappa}{M} \cdot \left(35 \frac{M}{c} \right)^2 = 92H$$

Bu kuch umumiy kuchning

$$\frac{F_{kapu}}{F} = \frac{92H}{420H} = 0,219 = 21,9 \%$$

qismini tashkil etadi.

4-masala: Spark avtomobilining haydovchi bilan birigalikdagi massasi $m=950$ kg ga teng. Dumalashdagi qarshilik koeffitsienti $f=0,02$ ga teng bo'lgan yo'lning gorizontal qismida harakatlanayotgan bu avtomobil motorning $F=380$ N doimiy tortish kuchi ta'sirida tezlanuvchan harakat qilmoqda. Havoning qarshilik koeffitsienti $\beta=0,14 \frac{kg}{m}$ ga teng. Erishish mumkin bo'lgan maksimal tezlikning 80% qiymatiga erishish uchun qancha vaqt sarflanadi? Bunda avtomobil qancha masofa bosib o'tadi? Erkin tushish tezlanishini $g=9,8 m/s^2$ deb oling.

Yechish: Masalani ishlash uchun avvalo maksimal tezlikning qiymatini ainqlaymiz.

$$g_{\max} = \sqrt{\frac{F - fmg}{\beta}} = \sqrt{\frac{380N - 0,02 \cdot 950kg \cdot 9,8 \frac{m}{s^2}}{0,14 \frac{kg}{m}}} = 37,2 \frac{m}{s}$$

So'ralgan vaqtini yuqoridagi (II.9') formuladan foydalanib topamiz.

$$\begin{aligned} t &= \frac{m}{2\beta g_{\max}} \cdot \ln \left| \frac{g_{\max} + g}{g_{\max} - g} \cdot \frac{g_{\max} - g_0}{g_{\max} + g_0} \right| = \frac{m}{2\beta g_{\max}} \cdot \ln \left| \frac{g_{\max} + 0,8g_{\max}}{g_{\max} - 0,8g_{\max}} \right| = \\ &= \frac{m}{2\beta g_{\max}} \cdot \ln 9 = \frac{950kg}{2 \cdot 0,14 \frac{kg}{m} \cdot 37,2 \frac{m}{s}} = 91,2 s \cdot 2,2 = 200 s = 3 \text{ min } 20 s. \end{aligned}$$

Endi esa so'ralgan masofa uzunligini ainqlash uchun (II.12') formuladan foydalanib topamiz.

$$s = \frac{m}{2\beta} \cdot \ln \left| \frac{g_{\max}^2 - g_0^2}{g_{\max}^2 - g^2} \right| = \frac{m}{2\beta} \cdot \ln \left| \frac{g_{\max}^2 - 0^2}{g_{\max}^2 - (0,8g_{\max})^2} \right| = \frac{950\kappa\varrho}{2 \cdot 0,14 \frac{\kappa\varrho}{m}} \cdot \ln 2,778 = 3466 m$$

5-masala: Massasi m ga teng bo'lgan engil avtomobilning biror ondag'i tezligi $g_0 = 40 \frac{m}{s}$ ga teng. Agar shu onda avtomobil bakidagi yoqilg'isi tugab qolsa, avtomobil sekinlanuvchan harakat qila boshlaydi. Bunda avtomobilning $g_1 = 0,5g_0$ tezlikka erishish uchun ketadigan vaqt t_1 hamda bosib o'tadigan yo'l s1 nimaga teng? Umumiy to'xtash vaqtini $t_{\text{to'xt}}$ hamda masofasini $s_{\text{to'xt}}$ nimaga teng? Avtomobil massasi $m = 1200\kappa\varrho$ ga, yo'lning harakatga qarshilik koeffitsientini $\mu = 0,015$ ga, havoning qarshilik koeffitsientini esa $\beta = 0,1 \frac{kg}{m}$ ga teng. Erkin tushish tezlanishini $g = 9,8 m/s^2$ deb oling.

Yechish: Masaladagi so'ralgan vaqt va masofalarni hisoblash uchun (II.11) va (II.12) formulalardan foydalanib topamiz. Dastlab t_1 hamda s_1 kattaliklarni hisoblaylik. Bunda avtomobil motori o'chgani uchun $F=0$ deb olamiz.

$$\begin{aligned} t_1 &= \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \operatorname{arctg} \left(\frac{\sqrt{\frac{\beta}{fmg - F}} \cdot (g_0 - g)}{1 + \frac{\beta}{fmg - F} \cdot g_0 g} \right) = \sqrt{\frac{m}{\beta f g}} \cdot \operatorname{arctg} \left(\frac{\sqrt{\beta fmg} \cdot (g_0 - g)}{fmg + \beta g_0 g} \right) = \\ &= \sqrt{\frac{1200kg}{0,1 \frac{kg}{m} \cdot 0,015 \cdot 9,8 \frac{m}{s^2}}} \cdot \operatorname{arctg} \left(\frac{\sqrt{0,1 \frac{kg}{m} \cdot 0,015 \cdot 1200kg \cdot 9,8 \frac{m}{s^2}} \cdot \left(40 \frac{m}{s} - 20 \frac{m}{s} \right)}{0,015 \cdot 1200kg \cdot 9,8 \frac{m}{s^2} + 0,1 \frac{kg}{m} \cdot 40 \frac{m}{s} \cdot 20 \frac{m}{s}} \right) = \\ &= 745 s \cdot \operatorname{arctg} \left(\frac{84}{256,4} \right) = 235 s = 3 \text{ min } 55 s. \end{aligned}$$

$$s_1 = \frac{m}{2\beta} \cdot \ln \left| \frac{F - (fmg + \beta g_0^2)}{F - (fmg + \beta g^2)} \right| = \frac{m}{2\beta} \cdot \ln \left| \frac{\beta g_0^2 + fmg}{\beta g^2 + fmg} \right| = \frac{1200 \kappa \varrho}{2 \cdot 0,1 \frac{\kappa \varrho}{m}}.$$

$$\cdot \ln \left| \frac{0,1 \frac{\kappa \varrho}{m} \cdot \left(40 \frac{m}{c} \right)^2 + 0,015 \cdot 1200 \kappa \varrho \cdot 9,8 \frac{m}{c^2}}{0,1 \frac{\kappa \varrho}{m} \cdot \left(20 \frac{m}{c} \right)^2 + 0,015 \cdot 1200 \kappa \varrho \cdot 9,8 \frac{m}{c^2}} \right| = 6000 m \cdot \ln \left| \frac{336,4}{216,4} \right| = 2647 m.$$

Endi esa umumiy to'xtash vaqtini t_{to'xt} hamda to'xtash masofasini s_{to'xt} ni aniqlaymiz. Bunda avtomobil motori o'chgani uchun F=0 deb hamda avtomobil yurib borib to'xtagani uchun g=0 deb olamiz.

$$t_{to'xt} = \frac{m}{\sqrt{\beta(fmg - F)}} \cdot \arctg \left(\frac{\sqrt{\frac{\beta}{fmg - F}} \cdot (g_0 - g)}{1 + \frac{\beta}{fmg - F} \cdot g_0 g} \right) = \sqrt{\frac{m}{\beta f g}} \cdot \arctg \left(\sqrt{\frac{\beta}{fmg}} \cdot g_0 \right) = \\ = \sqrt{\frac{1200 kg}{0,1 \frac{kg}{m} \cdot 0,015 \cdot 9,8 \frac{m}{s^2}}} \cdot \arctg \left(\sqrt{\frac{0,1 \frac{kg}{m}}{0,015 \cdot 1200 kg \cdot 9,8 \frac{m}{s^2}}} \cdot 40 \frac{m}{s} \right) = \\ = 745 s \cdot \arctg(0,9524) = 567 s = 9 \text{ min } 27 \text{ s.}$$

$$s_{to'xt} = \frac{m}{2\beta} \cdot \ln \left| \frac{F - (fmg + \beta g_0^2)}{F - (fmg + \beta g^2)} \right| = \frac{m}{2\beta} \cdot \ln \left| 1 + \frac{\beta g_0^2}{fmg} \right| = \frac{1200 kg}{2 \cdot 0,1 \frac{kg}{m}} \cdot \\ \cdot \ln \left| 1 + \frac{0,1 \frac{kg}{m} \cdot \left(40 \frac{m}{s} \right)^2}{0,015 \cdot 1200 kg \cdot 9,8 \frac{m}{s^2}} \right| = 6000 m \cdot \ln |1,907| = 3873 m.$$

XULOSA

Biz ushbu maqolada talabalarga umumiy tushunchalar berish maqsadida gorizontal tekislikda harakatlanayotgan jismga qarshilikli muhitning ta'sirini va bundagi harakat va tezlik tenglamalarini o'rgandik. Lekin, hayotda bundanda murakkabroq holatlar uchraydi. Masalan, qiya tekislik bo'ylab tepalikka ko'tarilayotgan yoki pastga tushayotgan avtomobilning ishqalanish va havo qarshiligi ta'siridagi harakatini o'rganish birmuncha murakkabdir. Undan tashqari havoning avtomobil harakatiga qarshilik kuchini ham tezlikning ikkinchi darajasi uchun (nisbatan yuqoriroq tezliklar uchun) o'rganduk. Haqiqatda esa real sharoitda avtomobil tezligi oshib borib biror kritik tezlikdan oshganda qarshilik kuchi $F_{qar} \sim g$ bog'lanishdan birdaniga $F_{qar} \sim g^2$ bog'lanishga o'tadi, shuningdek harakat va tezlik tenglamalari ham o'zgaradi. Bularni birqalikda yechilishini o'rganish talabalar uchun biroz murakkablik qiladi.

Qarshilikli muhitda jismning harakatini o'rganishda, biz jismdagi qarshilik kuchini va shuning uchun jismning tezlik o'zgarishini uning tezligining biror funksiyasi deb hisoblaymiz. Bunday qarshilik kuchlari odatda konservativ emas va kinetik energiya odatda issiqlik sifatida ajraladi. Bunday mavzuni o'rganish hamda ularga oid masalalar yechish talabalarni ob'ektiv reallikka yaqinlashtiradi hamda tasavvur qila olish qobiliyatini o'stiradi, shuningdek differential va intgeral hisob-kitob ishlariga ko'nikma hosil qilishda yordam beradi.

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